

An Improved MTL Modeling of Transformer Winding

S.M.H. Hosseini, M. Vakilian, G.B. Gharehpetian

Abstract-- This paper presents a new approach for modeling of the windings using Multi-conductor Transmission Line (MTL) theory. In this model loss factor coefficient ($\tan\delta$) and dielectric constant (ϵ) have been considered as frequency dependent parameters. The improved multi-conductor transmission line (MTL) theory has been employed to model a 900 MVA, 500 kV transformer windings. It is shown that the simulation result of model with frequency dependent loss factor has a good agreement with measurements results.

Keywords: Transformer winding, Fast transient, Multi-conductor transmission line, Loss factor.

I. INTRODUCTION

Fast transient overvoltages can occur in transformers, in a high frequency range which can extend to 1 MHz. One of the most suitable and feasible stages for evaluation of such phenomena by simulation of the transformer winding model, is the design stage. Using this model, a proper insulation design can be suggested and the risk of occurrence of overvoltages at the resonance frequencies can be minimized. The existing transient transformer models [1-3] can be categorized as: "Detailed lumped parameters Model" or "Multi-conductor Transmission Line (MTL) Model". The fundamental elements of the detailed model are the lumped RLC circuit elements. The upper frequency range for the validity of this model is few hundred kHz [2-4]. In order to extend this range to a few MHz, it is necessary to use a turn-to-turn modeling procedure instead of disk-to-disk modeling [4]. This procedure will result in a large scale system. It is difficult to simulate and to analyze such a sophisticated system especially in a reasonable time.

The other solution to this problem is the hybrid model built by a combination of detailed model and black box models [4]. In this model, due to application of a black box, the order of the network reduced substantially. However,

there is no detailed information available on some parts of winding which is included in the black box model. To overcome the above mentioned problems, the method of this paper has been proposed which is based on distributed parameter transmission line (MTL) theory. Using this method, the number of equations and the size of memory required for calculation of transient responses decreased significantly.

The proposed MTL model has frequency dependent parameters. Although frequency dependent modeling of transformer is discussed in the literature, however most of them are focused on the lumped parameters model. The published works on MTL modeling is mostly concentrated on modeling electrical machines [5-6] and also on transformer windings [3], [7-8], ignoring the frequency dependence of the parameters.

II. MTL MODEL

The Multi-conductor Transmission Line (MTL) theory deals with a network of N conductors coupled all together, characterized by its inductance matrix, $[L]$ and capacitance matrix, $[C]$. To represent the propagation phenomenon of a wave along this network, the transmission line equations have been used as follows:

$$\frac{d[U(x)]}{dx} = -j\omega[L][I(x)] \quad (1)$$

$$\frac{d[I(x)]}{dx} = -j\omega[C][U(x)] + j\omega[C_0]E_0 \quad (2)$$

Where, $[U(x)]$ and $[I(x)]$ represent the voltages and the currents of multi-conductor transmission line, respectively [7-8].

Fig. 1 shows a network, which is the combination of a set of transmission lines. These lines are geometrically in parallel, however electrically in series.

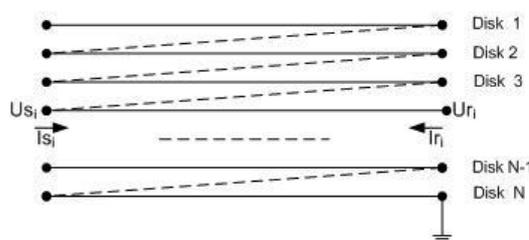


Fig. 1. Multi-conductor transmission line model

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As it can be seen in this figure, we have:

$$I_{r_i} = I_{s_{i+1}} \quad (3)$$

$$U_{r_i} = U_{s_{i+1}} \quad (4)$$

Now two different modeling techniques may be used:

- To model each disk with a multi-conductor transmission line, and making this equivalent to the model in which each turn is modeled as an extended transmission line.
- To model each disk in form of an extended single-conductor line.

In each of those, the required parameters, such as: surge impedance and propagation coefficient, can be estimated [7-8], [10-12].

In first step, the turns in each disk should be modeled with equivalent transmission lines. Assume that a sinusoidal power supply with the amplitude of E_0 and angular frequency of ω is connected to the input of the above model.

Solving the equations (1) and (2) results in:

$$U_i(x) = k_i E_0 + A_i \exp(-\Gamma(\omega)x) + B_i \exp(\Gamma(\omega)x) \quad (5)$$

$$I_i(x) = (1/z_i) \{A_i \exp(-\Gamma(\omega)x) - B_i \exp(\Gamma(\omega)x)\} \quad (6)$$

The coefficients, A_i and B_i , are the value of surge voltages amplitudes at the sending and receiving ends which can be determined from boundary conditions. k_i is the ratios of electrostatic induced voltages and Γ is the propagation coefficient.

Velocity of the electromagnetic wave in the insulator is:

$$v_s = \frac{c}{\sqrt{\epsilon_r}} \quad (7)$$

$$[L] = \frac{[C]^{-1}}{v_s^2} \quad (8)$$

Where, c is the light speed in vacuum and ϵ_r is the insulator relative dielectric constant. The detailed definitions of the distributed parameters are given in [12].

In second step, disks are modeled by a single-conductor transmission line and a set of similar equations derived as follows [7-10]:

$$U(x) = kE_0 + A \exp(-\Gamma(\omega)x) + B \exp(\Gamma(\omega)x) \quad (9)$$

$$I(x) = (1/z) \{A \exp(-\Gamma(\omega)x) - B \exp(\Gamma(\omega)x)\} \quad (10)$$

Where:

z_i : Surge impedances and

Γ : Coefficient of propagation

can be estimated by comparison of these two models. The following equations are the result of this comparison [7-10].

$$z_i = \frac{1}{v_s [C_0^i + C_1^i + 2K \{1 - \cos(\frac{\omega a}{v_s})\}]} \quad (11)$$

$$\Gamma = \frac{1}{v_s d} \sqrt{\frac{\omega}{2\sigma\mu} + \frac{\omega \tan \delta}{2v_s} + \frac{j\omega}{v_s}} \quad (12)$$

An algorithm has been developed in [7] which can model the disks of a winding by a single-conductor transmission line and then the overvoltages between the disks can be determined. Using these results, any arbitrary disk can be selected and modeled by a multi-conductor transmission line and then the overvoltages between the turns can be calculated.

III. FREQUENCY DEPENDENCE LOSS FACTOR AND DIELECTRIC CONSTANT

Both, the dielectric constant and the dielectric loss factor in the oil treated cellulose papers are affected by the change of the test voltage frequency. The dielectric constant when measured at lower permissible test temperature, demonstrates its highest variation as the test frequency increases. Figures 2 and 3 illustrate this variation for the loss factor and the dielectric constant of the oil impregnated cellulose at different temperatures over the frequency range of less than one megacycle per second [12].

As it can be seen in these figures, the dielectric constant remains approximately unchanged however the dielectric loss factor varies versus frequency. At $46^\circ C$, the dielectric constant is about 2.5 even when frequency changes from 0 to 1 MHz. At the same temperature, the loss factor can be estimated to be 0.006 in the frequency band of 0-40 kHz and then it increases linearly with frequency and at 1 MHz it is equal to 0.036 [12].

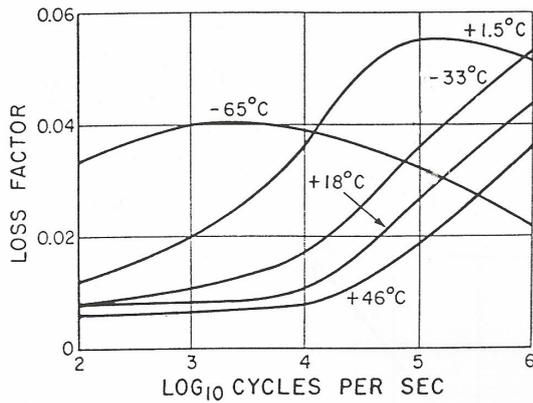


Fig. 2. Loss factor of oil impregnated cellulose versus frequency

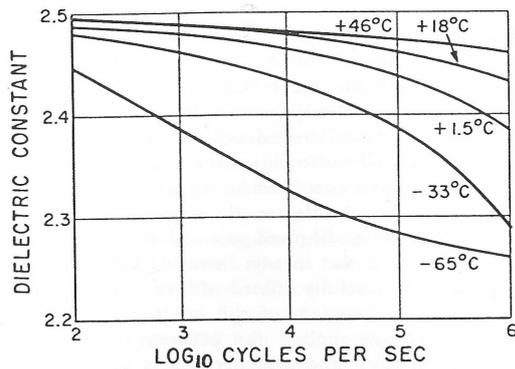


Fig. 3. Dielectric constant of oil impregnated cellulose versus frequency

IV. SIMULATION RESULTS

The improved MTL model presented in the last section is applied to the HV winding of a 900 MVA, 500 kV transformer. The technical specifications of this transformer are given in Table I. Fig. 4 shows the frequency dependent loss factor model employed in this simulation.

The transformer windings have been modeled by a set of transmission lines with frequency dependent parameters. It is assumed that a sinusoidal power supply with the amplitude of E_0 and angular frequency of ω is applied to the terminal of winding.

The absolute value of voltage between discs with respect to the input voltage can be determined for different type of transformer discs. Fig. 5 and Fig. 6 show inter-discs voltages for constant and frequency dependent loss factor, respectively. Fig. 7 and Fig. 8 show the same simulation results in 3dimensional graphs.

Comparing these simulation results with the measurement results of [7], it is obvious that the MTL model with frequency dependent loss factor has a better agreement with measurement results.

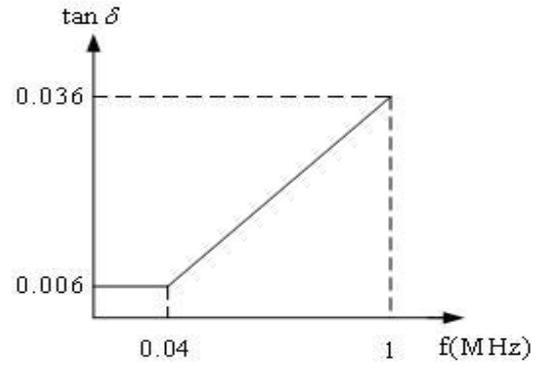


Fig. 4. Variation of $\tan \delta$ versus frequency

TABLE I

Technical specifications of IPC transformer windings

Disc date	Parameters related to surge propagation
Number of discs $m=12$	Dielectric constant of insulation $\epsilon_r = 2.65$
Turn length (i) $a = 6.83 \text{ m}$	Surge velocity $v_s = 184 \text{ m} / \mu_s$
Disc turns (i) $N = 17, 17, 21, 21, 23, 23, 23, 23, 21, 21, 17, 17$	Dielectric loss factor
	1. $\tan \delta = 0.02$ Constant
	2. $\tan \delta$ Variant versus f
	Conductor conductance $\delta = 5 \times 10^{-7} \text{ s/m}$
	$\mu = \mu_0 = 4\pi \times 10^{-7} \text{ H/m}$
	$d = 3.55 \text{ mm}$
Disc capacitance	Distributed capacitance parameter of coil 1
Disc - Disc (i) $C_m = 7500 \text{ p.F}$	Inter-turn (i) $k = 158 \text{ pF/m}$
Disc - ground (i) $C_g = 10 \text{ p.F}$	Conductor static plate (i) $C_0 = 5.7675 \text{ pF/m}$ (i) $C_1 = 64.59 \text{ pF/m}$

V. CONCLUSIONS

This paper presents an improved MTL model of transformer windings for fast transient studies. A HV winding of 500 kV, 900 MVA power transformer is modeled using the suggested model in a wide frequency range of 10 kHz to 1 MHz.

Simulation results have shown that MTL model with frequency dependent loss factor can represent the fast transient behavior of HV winding better than the models with constant $\tan \delta$.

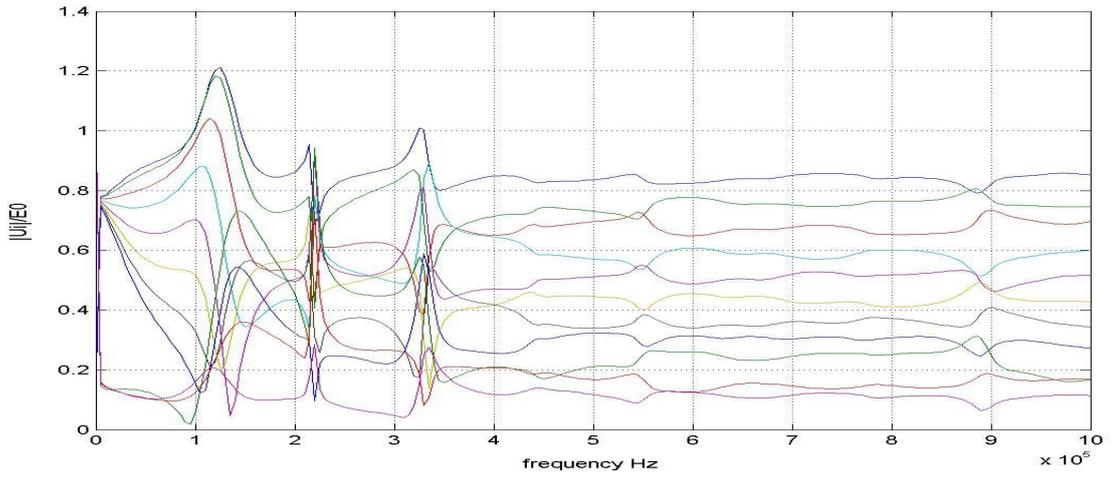


Fig. 5. Inter-disc voltages for constant $\tan \delta$ (equal to 0.02)

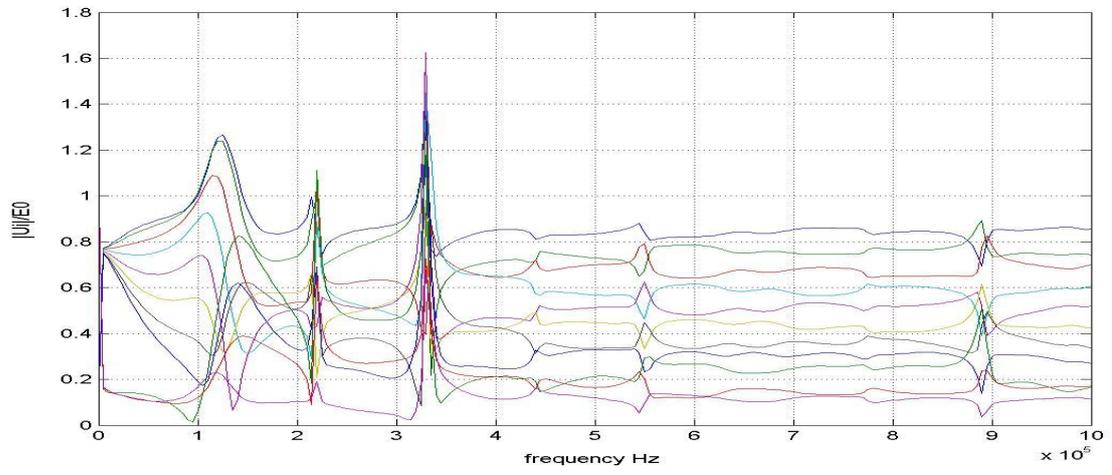


Fig. 6 Inter-disc voltages for frequency dependent $\tan \delta$

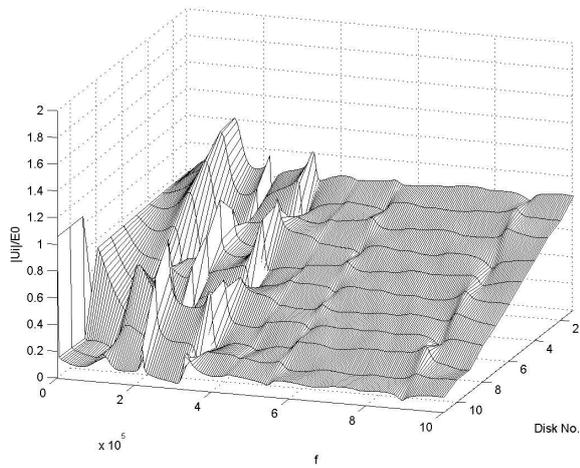


Fig. 7. 3D presentation of figure 5.

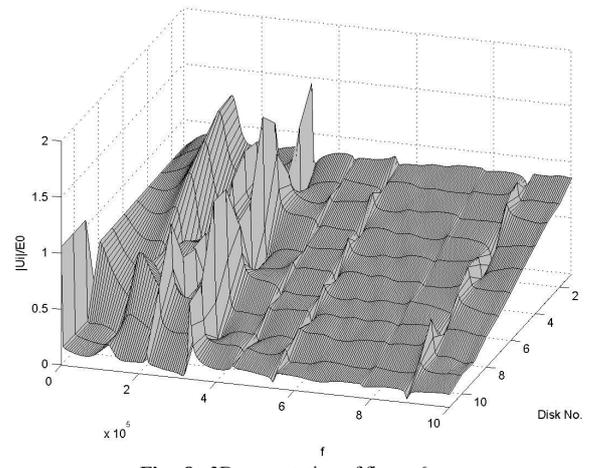


Fig. 8. 3D presentation of figure 6.

VI. REFERENCES

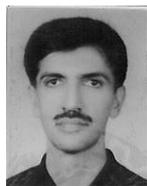
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VII. BIOGRAPHIES



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During September 2003 to September 2004 he was on leave of study at School of Electrical Engineering & Tel. of University of New South Wales, Sydney, Where he concentrated his research on study of PD signals propagation in XLPE cables.

At present he is also director of restructuring committee of Electrical Engineering education in Sharif University.



Gevork B. Gharehpetian was born in Tehran, in 1962. He received his BS and MS degrees in electrical engineering in 1987 and 1989 from Tabriz University, Tabriz, Iran and Amirkabir University of Technology (AUT), Tehran, Iran, respectively, graduating with First Class Honors. In 1989 he joined the Electrical Engineering Department of AUT as a lecturer. He received the Ph.D. degree in electrical engineering from Tehran University, Tehran, Iran, in 1996.

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